

Parion - spiral field w/ radius B at some surface

Recall, we have

$$B_r = B_0 \left(\frac{R_0}{r}\right)^2$$

$$B_\phi = -B_0 \frac{R_0}{r} \frac{R_0 \Omega_0 \sin \theta}{v_0}$$

} This is correct.

at $r=R_0$, $B_\phi \neq 0$.

Consider now having $B_\phi = 0$ @ $r=R_0$

Recall the boundary calculation we did. Apply again

$$\underline{\underline{E}}(r=R_0) = -\frac{1}{c} \underline{\underline{v}} \times \underline{\underline{B}} = -\frac{1}{c} \begin{vmatrix} \hat{r} & \hat{\theta} & \hat{\phi} \\ 0 & 0 & v_\phi \\ B_r & 0 & 0 \end{vmatrix}$$

$$= -\frac{1}{c} B_r v_\phi \hat{\theta}$$

$$\underline{\underline{E}}(r=R_0+\epsilon) = -\frac{1}{c} \begin{vmatrix} \hat{r} & \hat{\theta} & \hat{\phi} \\ v_0 & 0 & v_\phi \\ B_r & 0 & 0 \end{vmatrix}$$

$$= -\frac{1}{c} B_r v_\phi \hat{\theta}$$

continuous; so this is OK

thus, a better kinematic flow field is

$$\underline{v} = \begin{cases} v_\phi \hat{\phi} & ; r = R_0 \\ v_0 \hat{r} + v_\phi(r) \hat{\phi} & ; r > R_0 \end{cases}$$

lets also assume $v_0 = \text{constant}$.

Parker took $v_\phi = \text{constant}$ violating angular momentum cons.

see also Crocus, Parks

other books are correct Boyd & Sanderson also Priest

Consider the ϕ -component of the MHD momentum eq. (steady state)

$$(\underline{u} \cdot \nabla \underline{u})_\phi = (-\nabla P)_\phi + \left(\frac{1}{c} \underline{j} \times \underline{B} \right)_\phi - (\rho \underline{g})_\phi$$

vector identity

$$(\underline{A} \cdot \nabla \underline{B})_\phi = A_r \frac{\partial B_\phi}{\partial r} + \frac{A_\theta}{r} \frac{\partial B_\phi}{\partial \theta} + \frac{A_\phi}{r \sin \theta} \frac{\partial B_\phi}{\partial \phi} + \frac{A_\theta B_r}{r} + \frac{\cot \theta A_\phi B_\theta}{r}$$

$$\begin{aligned} \therefore u_r \frac{\partial u_\phi}{\partial r} + \frac{u_\theta}{r} \frac{\partial u_\phi}{\partial \theta} + \frac{u_\phi}{r \sin \theta} \frac{\partial u_\phi}{\partial \phi} + \frac{u_\phi u_r}{r} + \frac{u_\phi u_\theta}{r} \\ = -\frac{\partial p_r}{r \partial \phi} + 0 + 0 \end{aligned}$$

ignore
Mag. stresses

no grav. variation
in ϕ

$$\Rightarrow u_r \frac{\partial u_\phi}{\partial r} + \frac{u_\phi u_r}{r} = 0$$

$$\therefore \frac{\partial u_\phi}{\partial r} = -\frac{u_\phi}{r}$$

$u_\phi = \text{const}$ is not a solution
 can solve this, and we find

$$u_\phi = u_\phi(R_0) \frac{R_0}{r}$$

$$u_\phi = R_0 \Omega_0 \sin \theta \frac{R_0}{r} \quad (1)$$

we now solve mag. inducti eq.
using this form of \vec{v}_ϕ (V_ϕ)

$$\vec{v} = \begin{cases} R_0 \Omega_0 \sin \theta \hat{\phi} & r = R_0 \\ V_0 \hat{r} + R_0 \Omega_0 \sin \theta \frac{R_0}{r} \hat{\phi} & r > R_0 \end{cases}$$

solve $\frac{\partial \vec{b}}{\partial t} = \nabla \times (\vec{v} \times \vec{B}) = 0$
solve for \vec{B}

$$\vec{v} \times \vec{B} = \begin{pmatrix} \hat{r} & \hat{\theta} & \hat{\phi} \\ V_0 & 0 & V_\phi \\ B_r & 0 & B_\phi \end{pmatrix} \Bigg|$$

$$= (-V_0 B_\phi + V_\phi B_r) \hat{\theta}$$

$$\nabla \times (\vec{v} \times \vec{B}) = \frac{1}{r} \frac{\partial}{\partial r} [r (-V_0 B_\phi + V_\phi B_r)] \hat{\phi} = 0$$

$$\therefore -r V_0 B_\phi + r V_\phi B_r = \text{constant}$$

Also, $\nabla \cdot \mathbf{B} = 0$

$\Rightarrow \frac{1}{r^2} \frac{\partial}{\partial r}(r^2 B_r) = 0$ (no ϕ dependence)

$\therefore \boxed{B_r = B_0 \left(\frac{R_0}{r}\right)^2}$

@ $r = R_0$, we have

~~r~~ $R_0 v_\phi(R_0) B_0 = \text{constant}$

$\therefore -r v_\theta B_\phi + r v_\phi B_r = R_0 v_\phi(R_0) B_0$

$\Rightarrow -r v_\theta B_\phi + r \left(R_0 \Omega_0 \sin \theta \frac{R_0}{r} \right) B_0 \left(\frac{R_0}{r}\right)^2 = R_0^2 \Omega_0 \sin \theta B_0$

⋮

$\Rightarrow \boxed{B_\phi = -B_0 \frac{R_0}{r} \frac{R_0 \Omega_0 \sin \theta}{v_\theta} \left[1 - \left(\frac{R_0}{r}\right)^2 \right]}$

~~do~~

Parker spiral with fluctuations added

"WKB" limit \rightarrow small scale variations in \underline{B} due to plasma waves

"quasi-static" limit \rightarrow large scale variations in \underline{B} due to random motions of the magnetic footpoints
(~~P~~ Jokipii, Parker, 1969)

consider the ~~not~~ variations of \underline{B} due to "wiggling" of magnetic footpoints at the Sun (or some surface)

this is a time-dependent problem

still kinematic

i.e.
$$\underline{v} = \begin{cases} v_\theta(\theta, \phi) \hat{\theta} + (R_0 \Omega_0 \sin\theta + v_\phi') \hat{\phi} & r = R_0 \\ v_r \hat{r} & r > R_0 \end{cases}$$

for $r > R_0$, ~~the velocity is constant~~ it can be shown

$$\left. \begin{aligned} \left(\frac{\partial}{\partial t} + v_0 \frac{\partial}{\partial r} \right) (r^2 B_r) &= 0 \\ \left(\frac{\partial}{\partial t} + v_0 \frac{\partial}{\partial r} \right) (r B_\theta) &= 0 \\ \left(\frac{\partial}{\partial t} + v_0 \frac{\partial}{\partial r} \right) (r B_\phi) &= 0 \end{aligned} \right\} \begin{array}{l} \text{from} \\ \text{continuity} \\ \text{mag. induction} \\ \text{eq. \& } \nabla \cdot \mathbf{B} = 0 \end{array}$$

Use method of characteristics to solve

$$B_r(r, \theta, \phi, t) = B_r(r_0, \theta, \phi, t_0)$$

$$B_{\theta, \phi}(r, \theta, \phi, t) = B_{\theta, \phi}(r_0, \theta, \phi, t_0)$$

r_0, t_0 are related to r, t via the characteristic eq. which is from

$$\frac{dr}{dt} = v_0 \Rightarrow r - r_0 = v_0(t - t_0)$$

$$\boxed{t_0 = t - \frac{r - r_0}{v_0}}$$

also we apply B.C.'s at
the same as we did
before

$$\frac{B_\theta}{B_r} = \frac{V_\theta}{V_0} ; \quad \frac{B_\phi}{B_r} = \frac{V_\phi}{V_0} = \frac{R_0 \Omega \sin \theta + V_\phi'}{V_0}$$

General Solution

$$B_r = B_0 \left(\frac{R_0}{r} \right)^2$$

$$B_\theta = -B_0 \left(\frac{R_0}{r} \right) \frac{V_\theta(\theta, \phi, t_0)}{V_0}$$

$$B_\phi = -B_0 \left(\frac{R_0}{r} \right) \frac{R_0 \Omega \sin \theta + V_\phi'(\theta, \phi, t_0)}{V_0}$$

$$t_0 = t - \frac{r - R_0}{V_0}$$