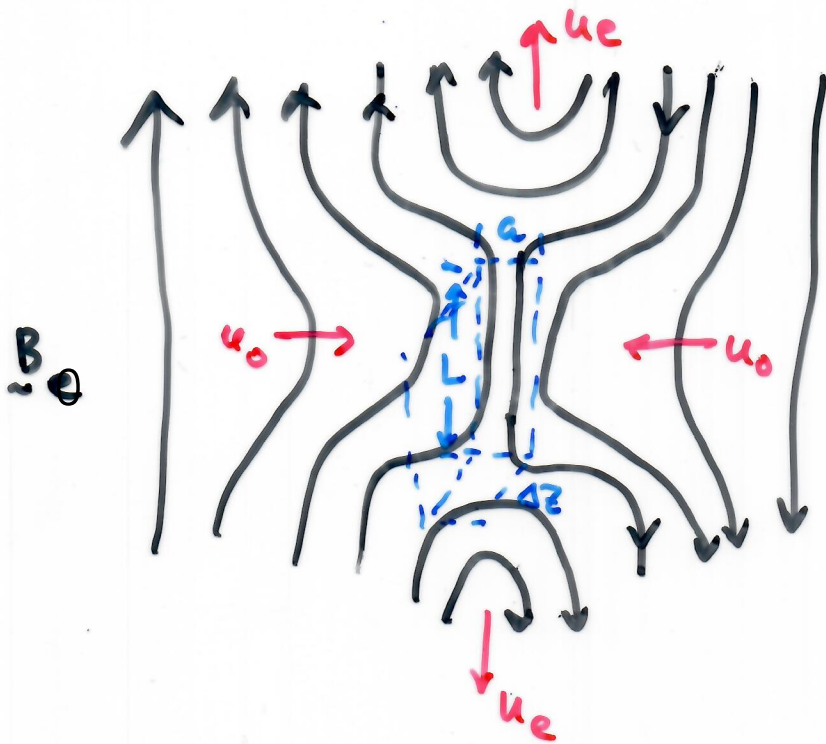


Sweet-Parker magnetic reconnection



Steady-state magnetic reconnection

$$\nabla \cdot \vec{u} = 0$$

\Rightarrow incompressible

$\Rightarrow \rho = \text{constant everywhere}$

- Conservation of particles

mass flux in = mass flux out

$$\rho u_0 L \Delta z = \rho u_e a \Delta z$$

$$\boxed{u_0 L = u_e a}$$

cons. of mass.

- Bernoulli's theorem - e.g. $\frac{1}{2} \rho u^2 + P = \text{constant along streamlines of flow.}$
- $\frac{1}{2} \rho u^2 + \frac{B^2}{8\pi} = \text{const. along streamlines for our case}$

$$\frac{1}{2} \rho u_0^2 + \frac{B_0^2}{8\pi} = \frac{1}{2} \rho u_e^2 + \frac{B_e^2}{8\pi} \quad -2-$$

$$\therefore \boxed{u_e = \left(\frac{B_0}{4\pi\rho}\right)^{1/2}} = \text{Alfvén speed.} \\ = v_A$$

What is u_0 ? (same as asking what is reconnection rate?)

balance energy dissipation rate with incoming energy flux

$$\underbrace{(\eta J^2)}_{\text{energy diss.}} \underbrace{L \Delta z a}_{\text{volume}} = \underbrace{\frac{B^2}{8\pi}}_{\text{energy flux}} \underbrace{L \Delta z}_{\text{area}}$$

$$J = \frac{c}{4\pi} \frac{B}{a} \approx \frac{c}{4\pi} \frac{B}{L}$$

$$u_0 = \frac{2\eta c^2}{4\pi a}$$

recall $a = \frac{u_0}{u_e} L$

$$\Rightarrow u_0 = \frac{2\eta c^2}{4\pi \left[\frac{u_0}{u_e} L\right]}$$

$$\Rightarrow u_0^2 = \frac{2\eta c^2}{4\pi L} u_e = \frac{2\eta c^2}{4\pi L} v_A$$

$$\Rightarrow u_0 = \left(\frac{2\gamma c^2}{4\pi L} v_A \right)^{1/2} \quad -3-$$

recall $R_m = \text{magneti. Reynolds \#}$

$$= \left(\frac{4\pi L v_A}{\gamma c^2} \right)$$

$$= \left(\frac{2}{R_m} v_A^2 \right)^{1/2}$$

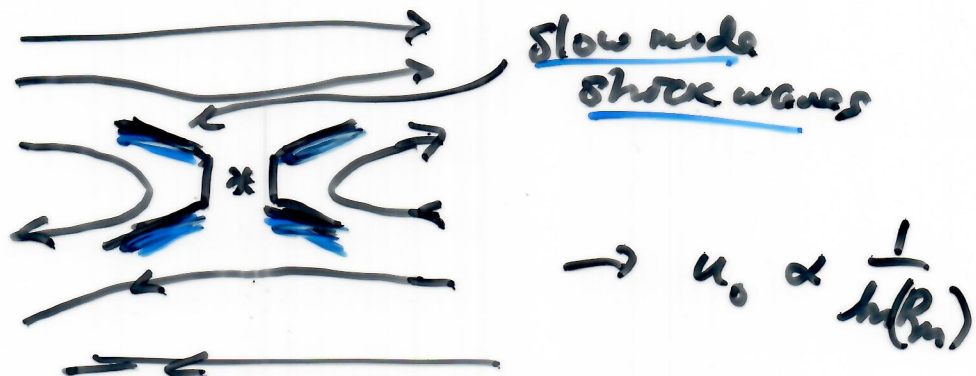
$$u_0 = \left(\frac{2}{R_m} \right)^{1/2} v_A$$

Reconnection rate
in Sweet-Parker model

Solar atm. $R_m \sim 10^9$

$$\Rightarrow u_0 \ll v_A$$

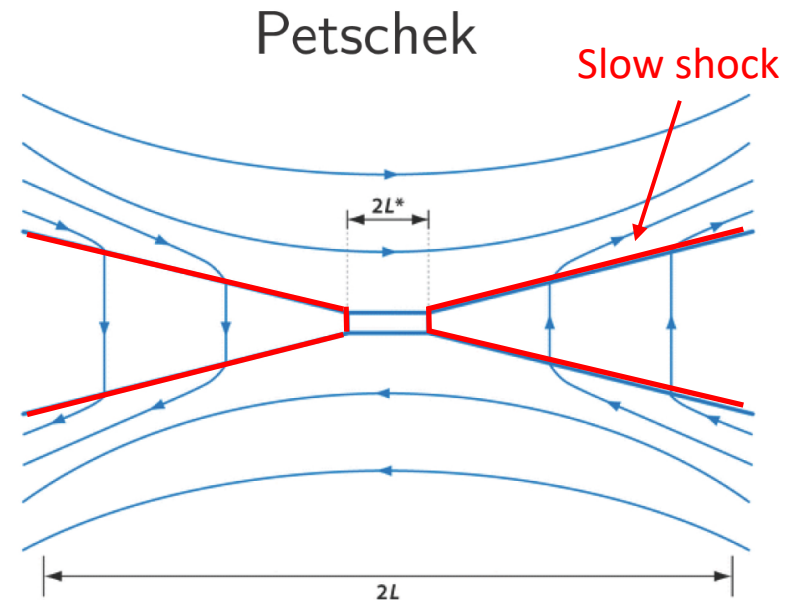
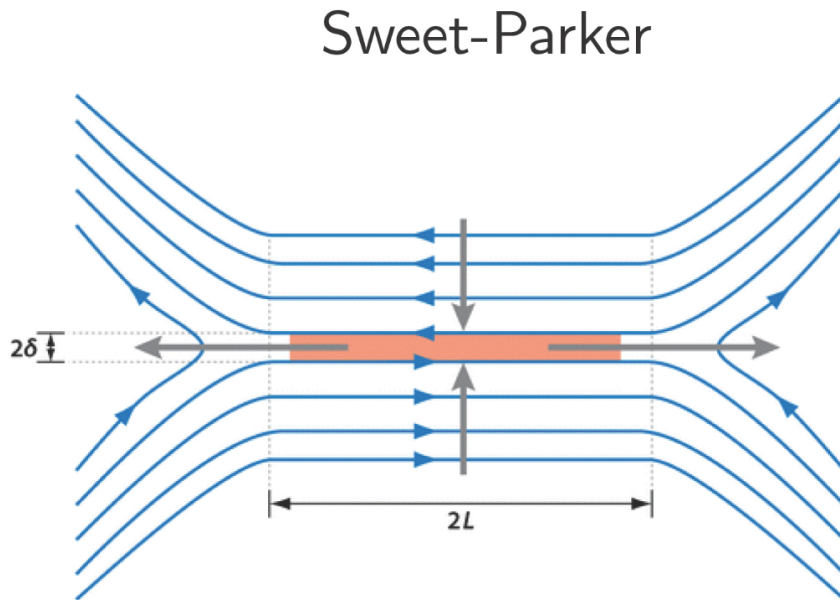
* Petschek model reconnection



* more recent

HALL MHD \rightarrow mostly solves problem
formation of magnetic "islands" \rightarrow turbulence

- Sweet-Parker reconnection predicts a much slower reconnection rate than observed in solar flares and Earth's magnetosphere
 - Solar flares release energy in a time frame of a few to tens of minutes. Sweet-Parker predicts it would be months. This model cannot work for most astrophysical situations.
- Petschek (1964) proposed a different model, involving slow-mode shocks, allowing for a more-localized reconnection region – and X-point type geometry. The reconnection rate scales as $1/\ln(R_m)$ – fast reconnection.



Zweibel & Yamada (2009)

- Petchek reconnection is not observed (in space or laboratory plasmas) to occur, thus this idea, is not the explanation for fast reconnection seen in space plasmas.
- So-called “Hall” reconnection does seem to agree with laboratory and space plasmas.
- What is “Hall” reconnection? To answer, this, consider the lecture on Feb 10 concerning the electric field in MHD. At the bottom of page 7 of those lecture notes, we wrote:

$$\vec{E} = -\frac{1}{c}\vec{U} \times \vec{B} + \frac{1}{nec}\vec{J} \times \vec{B} + \frac{1}{ne}\nabla P_e$$

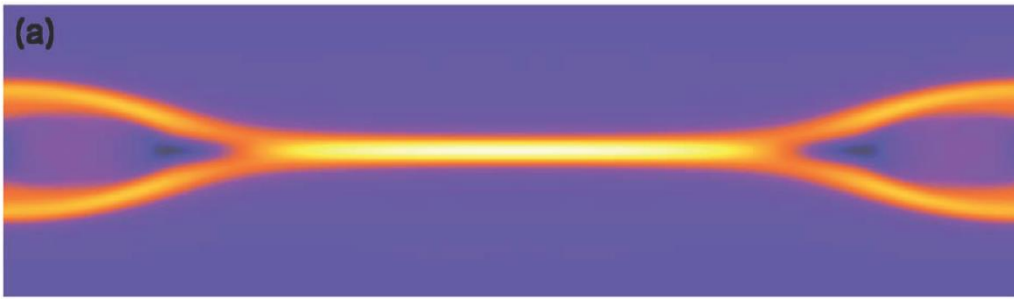
Ideal MHD term

HALL term

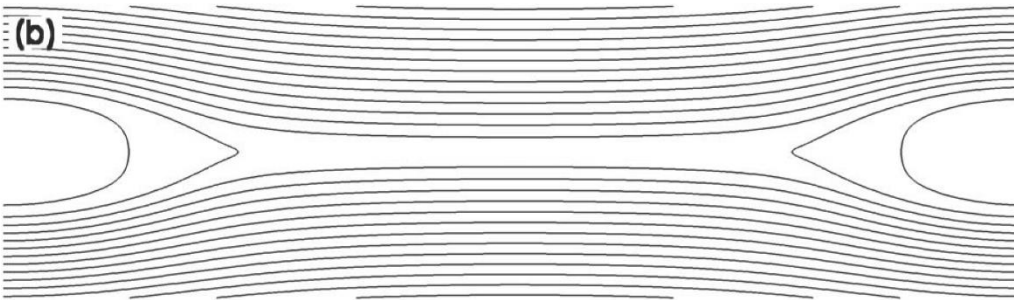
Polarization E field

Numerical Simulations

J

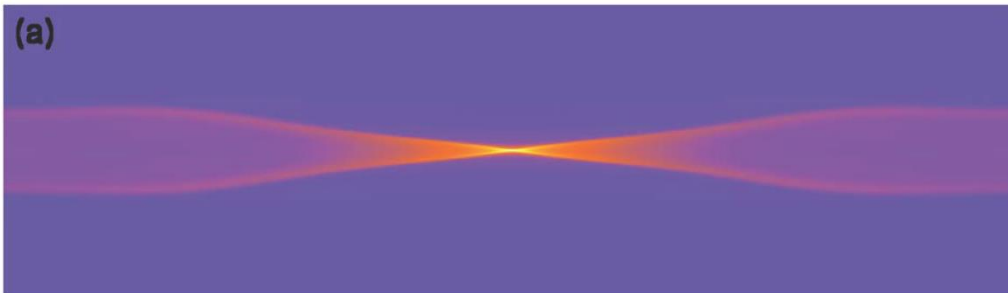


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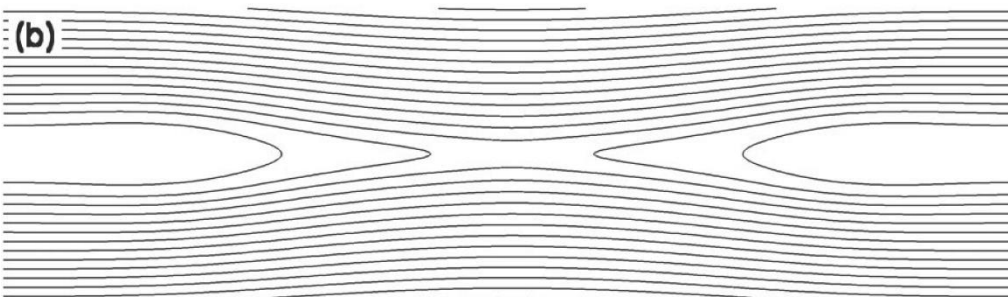


Hall term OFF:
resistive MHD.
Sweet-Parker-like

J



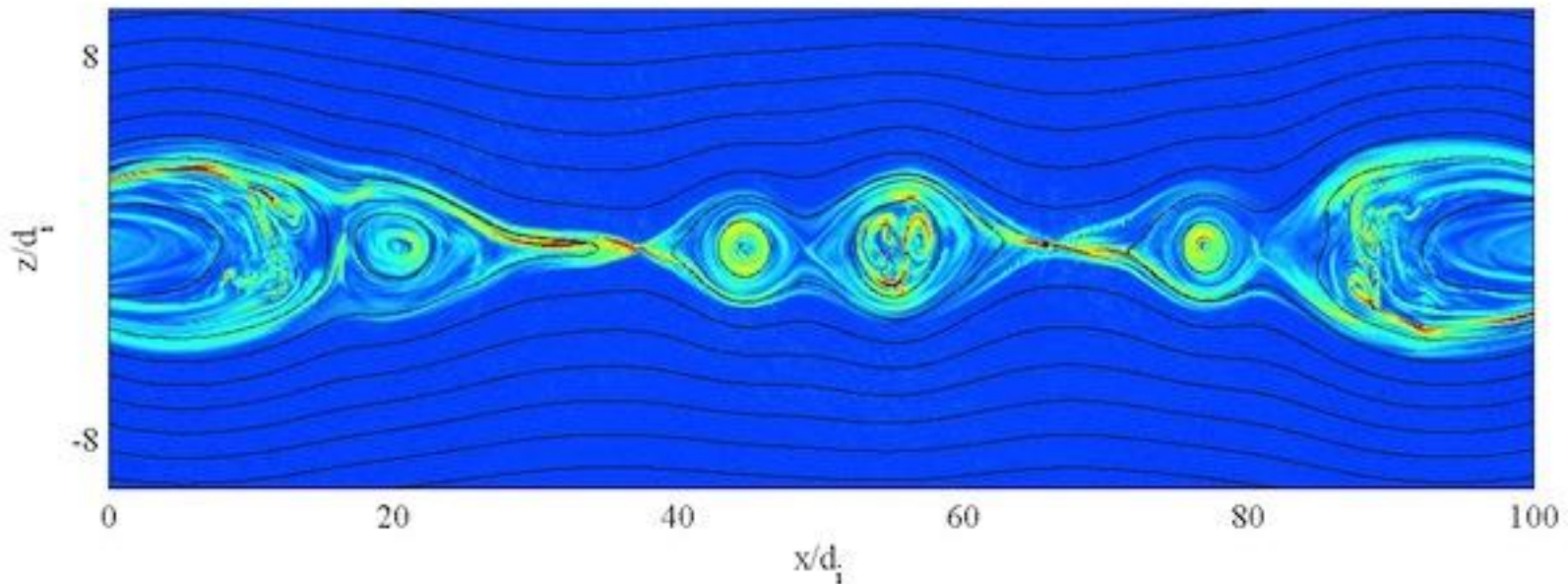
B



Hall term ON: fast
reconnection.
X-point geometry.

- The inclusion of the Hall term can lead to a “tearing-mode” instability for thin current sheets at small scales.
- This has been shown from fully kinetic numerical simulations to lead to the formation of “magnetic islands”, especially in the so-called “high-guide-field limit” (the guide field is the out of plane component of the magnetic field. High guide field is when this field dominates the in-plane magnetic field)

Current density, J , in a high-“guide-field” kinetic numerical simulation



Plasma Waves

$$\delta \underline{v}(\underline{x}, t) = \delta \underline{v}(\underline{k}, \omega) e^{i \underline{k} \cdot \underline{x} - i \omega t + \phi}$$

\underline{k} = wave vector $\lambda = \frac{2\pi}{|\underline{k}|}$, wavelength
 ω = wave frequency $T = \frac{2\pi}{\omega}$, wave period
 ϕ = phase angle

$\delta \underline{v}$ = amplitude + polarization
 \hat{z} → refers to direction of prop. (forward plane waves)

example

$$\delta \underline{v}(\underline{k}, \omega) = |\delta \underline{v}| (\hat{x} - i \hat{y})$$

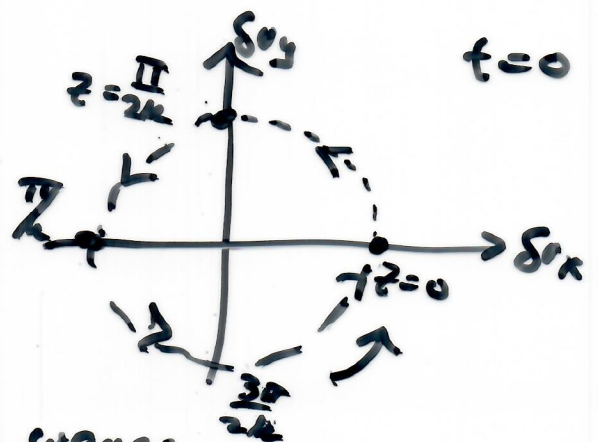
and propagation along \hat{z}
circularly polarized plane wave

take $\underline{k} = k \hat{z}$
 $\phi = 0$

$$\delta v_x = \delta v \cos(kz - \omega t)$$

$$\delta v_y = \delta v \sin(kz - \omega t)$$

right-hand ~~linearly~~ polarized wave.



This is a right-hand polarized, forward ⁻⁵⁻
propagating plane wave

$$\omega = \underline{k} \cdot \underline{v}_p \quad \underline{v}_p = \text{phase velocity}$$

$$d\omega = d\underline{k} \cdot \underline{v}_g \quad \underline{v}_g = \text{group velocity}$$

Recall MHD equations

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \underline{u}) = 0$$

$$\rho \frac{\partial \underline{u}}{\partial t} + \rho \underline{u} \cdot \nabla \underline{u} = -\nabla P + \frac{1}{4\pi} (\nabla \times \underline{B}) \times \underline{B} - \rho \underline{g}$$

$$\left(\frac{\partial}{\partial t} + \underline{u} \cdot \nabla \right) \left(\frac{P}{\rho} \right) = 0$$

$$\frac{\partial \underline{B}}{\partial t} = \nabla \times (\underline{u} \times \underline{B})$$

Perturb this by

$$\rho = \rho_0 + \rho' ; \quad P = P_0 + P'$$

$$\underline{u} = \underline{u}' ; \quad \underline{B} = \underline{B}_0 + \underline{B}'$$

$\rho', \underline{u}', P', \underline{B}'$
are
small
compared
to unperturbed

substitute into MHD eq's

-6-

Continuity

neglect
second-order
terms!

$$\frac{\partial}{\partial t}(\rho_0 + \rho') + \nabla \cdot [(\rho_0 + \rho') \underline{u}'] = 0$$

$$\Rightarrow \boxed{\frac{\partial \rho'}{\partial t} + \rho_0 \nabla \cdot \underline{u}' + \underline{u}' \cdot \nabla \rho_0 = 0} \quad (1)$$

Momentum eq.

$$\begin{aligned} (\rho_0 + \rho') \frac{\partial}{\partial t}(\underline{u}') + (\rho_0 + \rho') \underline{u}' \cdot \nabla \underline{u}' \\ = -\nabla(\rho_0 + \rho') + \frac{1}{4\pi} [\nabla \times (\underline{B}_0 + \underline{B}')] \times (\underline{B}_0 + \underline{B}') \\ - (\rho_0 + \rho') \underline{g} \end{aligned}$$

h.s. equil.

$$\boxed{\rho_0 \frac{\partial \underline{u}'}{\partial t} = -\nabla \rho' + \frac{1}{4\pi} (\nabla \times \underline{B}_0) \times \underline{B}' - \rho' \underline{g}} \quad (2)$$

$$\boxed{\nabla \rho_0 = -\rho_0 \underline{j}}$$

$$\boxed{\nabla \times \underline{B}_0 = 0} \quad \text{unif. back field}$$

Energy eq. → more tedious, but leads

$$\boxed{\frac{\partial \rho'}{\partial t} + \underline{u}' \cdot \nabla \rho_0 - c_s^2 \left(\frac{\partial \rho'}{\partial t} + \underline{u}' \cdot \nabla \rho_0 \right) = 0} \quad (3)$$

$$\begin{aligned} c_s &= \left(\frac{\delta \rho_0}{\rho_0} \right)^{1/2} \\ &= \text{Sound Speed} \end{aligned}$$

$$\frac{\partial \vec{B}'}{\partial t} = \nabla \times (\vec{a}' \times \vec{B}_0) \quad (4)$$

take $\partial/\partial t$ of (2), then substitute from (1), (3), (4) to give the general wave equation

$$\frac{\partial^2 \vec{a}'}{\partial t^2} = c^2 \nabla (\nabla \cdot \vec{a}') - (\gamma - 1) \nabla (\nabla \cdot \vec{a}') - \gamma \nabla^2 \vec{a}' + \frac{1}{4\pi\mu_0} [\nabla \times \nabla \times (\vec{a}' \times \vec{B}_0)] \times \vec{B}_0$$

~~and~~

Recap

the general eq. for perturbed \underline{u}' is (wave eq.)

$$\frac{\partial^2 \underline{u}'}{\partial t^2} = c_s^2 \nabla (\nabla \cdot \underline{u}') - (\gamma - 1) g (\nabla \cdot \underline{u}') - g \nabla \underline{u}' + \frac{1}{4\pi p_0} [\nabla \times \nabla \times (\underline{u}' \times \underline{B}_0)] \times \underline{B}_0$$

(general wave eq.)

assume plane-wave solution

$$\underline{u}'(\underline{x}, t) = \underline{u}'(\underline{k}, \omega) e^{i\underline{k} \cdot \underline{x} - i\omega t + \phi}$$

$$\nabla \rightarrow i\underline{k}$$

$$\frac{\partial}{\partial t} \rightarrow -i\omega$$

$$-\omega^2 \frac{\partial^2 \underline{u}'}{\partial t^2} = -c_s^2 \underline{k} (\underline{k} \cdot \underline{u}') - (\gamma - 1) g (\underline{k} \cdot \underline{u}') (-i\underline{k})$$

$$-ig \underline{k} \underline{u}' = \frac{1}{4\pi p_0} [\underline{k} \times \underline{k} \times (\underline{u}' \times \underline{B}_0)] \times \underline{B}_0$$

general dispersion relation for MHD waves

$$\omega^2 \underline{u}' = c_s^2 \underline{k} (\underline{k} \cdot \underline{u}') - i\underline{k} (\gamma - 1) g (\underline{k} \cdot \underline{u}') + ig \underline{k} \underline{u}' + \frac{1}{4\pi p_0} [\underline{k} \times \underline{k} \times (\underline{u}' \times \underline{B}_0)] \times \underline{B}_0$$

Sound Waves

-2-

$$\text{take } \underline{g} = 0, \underline{B}_0 = 0$$

$$\frac{\omega^2}{c_s^2} \underline{u}' = \underline{k} (\underline{k} \cdot \underline{u}')$$

dot into \underline{k}

$$\left(\frac{\omega^2}{c_s^2} - k^2 \right) (\underline{k} \cdot \underline{u}') = 0$$

$$\text{get } \omega^2 = k^2 c_s^2 \quad ; \quad v = \pm k c_s$$

$$\text{if } \underline{k} \cdot \underline{u}' \neq 0$$

these are sound waves.

$$|v_{\text{phase}}| = \pm c_s$$

$$v_g = \pm c_s$$

one then exists
to compressibility
of gas.

$$\underline{k} \cdot \underline{u}' \neq 0 \Rightarrow \nabla \cdot \underline{u}' \neq 0$$

compressible

Magnetic Waves

-3-

Intuitive picture

recall the driving force is $\frac{1}{c} \underline{J} \times \underline{B}$

this has a pressure part & tension part.

Consider tension. From physics of waves on strings, it is found

$$v_p = \left(\frac{T}{\rho^*} \right)^{1/2}$$

T = tension of string,
 ρ^* = mass per length of the string

for the analog to MHD

$$T \rightarrow \frac{B^2}{4\pi}$$

$$\rho^* \rightarrow \rho$$

$$v_p = \left(\frac{B^2/4\pi}{\rho} \right)^{1/2} = \left(\frac{B^2}{4\pi\rho} \right)^{1/2} = C_A$$

Alfvén
speed.

Consider pressure part

recall $P/\rho^2 = \text{const.}$

$$C_s^2 = \frac{\delta P}{\rho}$$

analog
sound
pressure
waves

it can be
shown

$B/\rho = \text{const.}$ (normal to \underline{B})
derived from
frozen flux
theor.

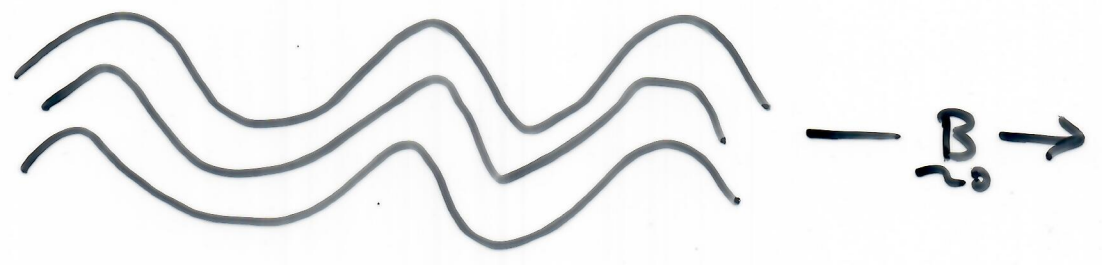
$\therefore B^2/\rho^2 = \text{const.}$

$\frac{B^2/8\pi}{\rho^2} = \text{const.} \quad P_m$

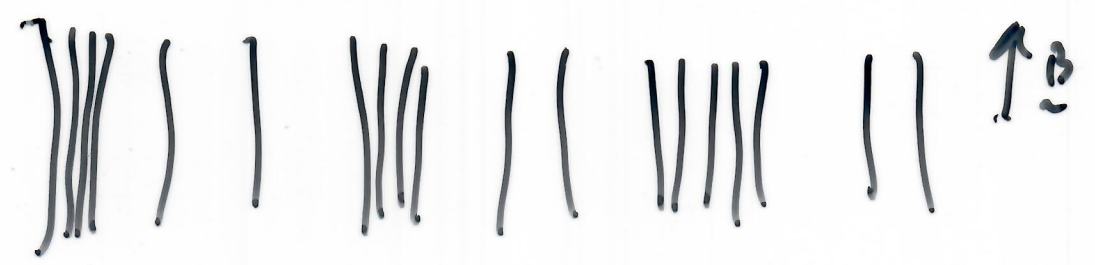
$$c_w^2 = \frac{\delta P_m}{\rho} = \frac{\delta B^2/8\pi}{\rho} = \frac{\delta}{2} \frac{B^2}{4\pi\rho} = \frac{\delta}{2} C_A^2$$

$\delta = 2$, the pressure part of $\underline{J} \times \underline{B}$ force is analogous to waves moving with speed C_A "same"

transverse



pressure



variations in field strength \rightarrow